

# Scalar, Vector and DTC Control of Three-Phase Induction Motor Drive

#### Model No.: NIADO1

### **Unique Features**

- Complete advanced learning platform
- Self-written program
- Model based program
- MATLAB/C language coding support
- Rapid development of new control algorithm

#### **Control Methods**

Scalar Control (Open & Closed Loop) Vector Control Direct Torque Control

### Controller

ARM Cortex M4 32 bit Microcontrollers

Generic industry standard platform

### **Drives Consist of**

Three phase sq. cage induction motor with mechanical loading

Digital controller based on STM32F407VG uC

High power rectifier, DC link capacitor, inverter

Sensing circuits for AC/DC current, DC voltage and speed Performance Investigation of Computerized Scalar, Vector and DTC Control Technique of Three-Phase Induction Motor Drive

Category: Advanced Electrical Drives

Electrical drivefor studying different control techniques of induction motor control using latest ARM Cortex M4 32 bit Microcontrollers.

# Motor Controller



ARM Cortex M4 32-bit microcontroller for programming (STM32F407VGT6 microcontroller featuring 32-bit ARM Cortex-M4F core)

STM32F407VGT6 ARM Cortex-M4 Board featuring 32-bit ARM Cortex-M4F core, 168 MHz, 1 MB Flash, 192 KB RAM in an LQFP100 package.

On-board ST-LINK/V2 for programming and debugging with selection mode switch, Power supply: through USB bus or from an external.

On-board ADC, DAC, USB/JTAG terminal facility

Port pins are routed to header on mother board for easy connection and having:

8 General purpose input lines, 8 General purpose output lines, 16x2 LCD interface, 5 keys interface.

3 high speed digital outputs and 2 High speed digital input lines. 6 PWM outputs, 3 QEI inputs.

SPI bus for SPI slave interface,

9 Analog inputs, 2 Analog Universal outputs

### **National Infotech**

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Input – 415V AC, Output – 3 Phase 400V, 10A suitable for 1.5 HP AC motor having proper heat dissipation arrangements

1200 V, 25 A diode rectifier with electrolyte DC capacitor for Input AC-DC conversion,

3 Phase Inverter Power Module with IGBT Rating @ 1200 V, 30 Amp with detailed protection and snubber circuits arrangement, interface circuit arrangement with controller using appropriate connectors, On-board driver circuit with protection and PWM isolation, IGBT with desaturation protection against overload and short-circuit.

Over current trip circuit is provided with trip status indicator, RESET switch.

Sensing circuit for three AC output currents, one DC current and one DC voltage. All connections terminated with banana connector.

### **Motor Setup**



Motor setup consist of Benn make

1.5 HP, 415 V, 1440 RPM, 50 Hz, Star connected with all 6 wires brought out for 230 V Delta connection, 3-Phase Sq. cage induction Motor with Mechanical loading arrangement.

Essential speed and other sensors as per control and feedback requirement.

# **Computer and Programing Arrangement**

Complete arrangement with personal computer having minimum following configuration is provided for programming the drive.

Intel Core-i3 (6th generation) 3.3 GHz processor, Mother Board - ASUS/GIGA-BITE or equivalent, RAM- 8 GB, Hard disk min.- 500 GB, DVD writer, Screen (18.5 Inch) – LG or equivalent, with required essential accessories.

Facility for self-written C program as well as model based programming.



# Speed Control of 5-phase Induction Motor using ARM Cortex 32-bit Microcontroller

### Model No.: NIADO2

Category: Advanced Electrical Drives

### **Unique Features**

- Complete advanced learning platform
- Self-written program
- Model based program
- MATLAB/C language coding support
- Rapid development of new control algorithm
- Scalar Control(Open & Closed Loop)

# Controller

ARM Cortex M4 32 bit Microcontrollers

Generic industry standard platform

### **Drives Consist of**

Five phase sq. cage induction motor with mechanical loading

Digital controller based on STM32F407VG uC

High power rectifier, DC link capacitor, inverter

Sensing circuits for AC/DC current, DC voltage and speed

# Performance Investigation of Computerized Speed Control of 5-phase Induction Motor using ARM Cortex 32-bit Microcontroller

Electrical drivefor studying speed control of 5-phase induction motor using latest ARM Cortex M4 32 bit Microcontrollers.

# Motor Controller



ARM Cortex M4 32-bit microcontroller for programming (STM32F407VGT6 microcontroller featuring 32-bit ARM Cortex-M4F core)

STM32F407VGT6 ARM Cortex-M4 Board featuring 32-bit ARM Cortex-M4F core, 168 MHz, 1 MB Flash, 192 KB RAM in an LQFP100 package.

On-board ST-LINK/V2 for programming and debugging with selection mode switch, Power supply: through USB bus or from an external.

On-board ADC, DAC, USB/JTAG terminal facility

Port pins are routed to header on mother board for easy connection and having:

8 General purpose input lines, 8 General purpose output lines, 16x2 LCD interface, 5 keys interface.

3 high speed digital outputs and 2 High speed digital input lines. 6 PWM outputs, 3 QEI inputs.

SPI bus for SPI slave interface,

9 Analog inputs, 2 Analog Universal outputs

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# High Power Module with Protection



Input – 415V AC, Output – 5 Phase 200V, 10A suitable for 1.5 HP 5-phase AC motor having proper heat dissipation arrangements

1200 V, 25 A diode rectifier with electrolyte DC capacitor for Input AC-DC conversion,

3 Phase Inverter Power Module with IGBT Rating @ 1200 V, 30 Amp with detailed protection and snubber circuits arrangement, interface circuit arrangement with controller using appropriate connectors, On-board driver circuit with protection and PWM isolation, IGBT with desaturation protection against overload and short-circuit.

Over current trip circuit is provided with trip status indicator, RESET switch.

Sensing circuit for three AC output currents, one DC current and one DC voltage. All connections terminated with banana connector.

# **Motor Setup**



Motor setup consist of Benn make

1.0 – 1.5 HP / 5 Phase / 100 V - 200 V / 1400 RPM / Starconnected / 50 Hz. / SPDP / Foot Mounted /Ins. Cl. B / Singleshaft extended / Sq. Cage Induction Motor with Mechanicalloading arrangement having linear scales

Essential speed and other sensors as per control and feedback requirement.

# **Computer and Programing Arrangement**

Complete arrangement with personal computer having minimum following configuration is provided for programming the drive.

Intel Core-i3 (6th generation) 3.3 GHz processor, Mother Board - ASUS/GIGA-BITE or equivalent, RAM- 8 GB, Hard disk min.- 500 GB, DVD writer, Screen (18.5 Inch) – LG or equivalent, with required essential accessories.

Facility for self-written C program as well as model based programming.



# Performance Investigation of Digitally controlled BLDC Motor Drive

### Model No.: NIADO3

### **Unique Features**

- Complete advanced learning platform
- Self-written program
- Model based program
- MATLAB/C language coding support
- Rapid development of new control algorithm
- Controller: ARM Cortex M4 32 bit Microcontrollers

#### **Drives Consist of**

0.5 HP BLDC motor with mechanical loading

Digital controller based on STM32F407VG uC

High power rectifier, DC link capacitor, inverter

Sensing circuits for AC/DC current, DC voltage and speed

### Contact

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### Performance Investigation of Digitally controlled BLDC Motor Drive

**Category: Advanced Electrical Drives** 

Electrical drive for studying control of Brushless DC motor drive using latest ARM Cortex M4 32 bit Microcontrollers.

# Motor Controller



ARM Cortex M4 32-bit microcontroller for programming (STM32F407VGT6 microcontroller featuring 32-bit ARM Cortex-M4F core)

STM32F407VGT6 ARM Cortex-M4 Board featuring 32-bit ARM Cortex-M4F core, 168 MHz, 1 MB Flash, 192 KB RAM in an LQFP100 package.

On-board ST-LINK/V2 for programming and debugging with selection mode switch, Power supply: through USB bus or from an external.

On-board ADC, DAC, USB/JTAG terminal facility

Port pins are routed to header on mother board for easy connection and having:

8 General purpose input lines, 8 General purpose output lines, 16x2 LCD interface, 5 keys interface.

3 high speed digital outputs and 2 High speed digital input lines. 6 PWM outputs, 3 QEI inputs.

SPI bus for SPI slave interface,

9 Analog inputs, 2 Analog Universal outputs

# High Power Module with Protection



Input – 230V single-phase AC, Output – 3 Phase 50V, 10A suitable for BLDC motor having proper heat dissipation arrangements

1200 V, 25 A diode rectifier with electrolyte DC capacitor for Input AC-DC conversion,

3 Phase Inverter Power Module with IGBT Rating @ 1200 V, 30 Amp with detailed protection and snubber circuits arrangement, interface circuit arrangement with controller using appropriate connectors, On-board driver circuit with protection and PWM isolation, IGBT with desaturation protection against overload and short-circuit.

Over current trip circuit is provided with trip status indicator, RESET switch.

Sensing circuit for three AC output currents, one DC current and one DC voltage. All connections terminated with banana connector.

# **Motor Setup**



Motor setup consist of Benn make

0.5~HP / 48~V / 1500~RPM / BLDC Motor with mechanical loading arrangement having inbuilt sensor

Essential speed and other sensors as per control and feedback requirement.

### **Computer and Programing Arrangement**

Complete arrangement with personal computer having minimum following configuration is provided for programming the drive.

Intel Core-i3 (6th generation) 3.3 GHz processor, Mother Board - ASUS/GIGA-BITE or equivalent, RAM- 8 GB, Hard disk min.- 500 GB, DVD writer, Screen (18.5 Inch) – LG or equivalent, with required essential accessories.

Facility for self-written C program as well as model based programming.



# Performance Investigation of Digitally controlled PMSM Vector Control Drive

#### Model No.: NIADO4

### **Unique Features**

- Complete advanced learning platform
- Self-written program
- Model based program
- MATLAB/C language coding support
- Rapid development of new control algorithm

#### **Control Methods**

Scalar Control (Open & Closed Loop) Vector Control

#### Controller

ARM Cortex M4 32 bit Microcontrollers

Generic industry standard platform

#### **Drives Consist of**

1 HP PMSM with mechanical loading

Digital controller based on STM32F407VG uC

High power rectifier, DC link capacitor, inverter

Sensing circuits for AC/DC current, DC voltage and speed

# Performance Investigation of Digitally controlled PMSM Vector Control Drive

Category: Advanced Electrical Drives

Electrical drive for studying different control techniques of PMSM motor control using latest ARM Cortex M4 32 bit Microcontrollers.

# Motor Controller



ARM Cortex M4 32-bit microcontroller for programming (STM32F407VGT6 microcontroller featuring 32-bit ARM Cortex-M4F core)

STM32F407VGT6 ARM Cortex-M4 Board featuring 32-bit ARM Cortex-M4F core, 168 MHz, 1 MB Flash, 192 KB RAM in an LQFP100 package.

On-board ST-LINK/V2 for programming and debugging with selection mode switch, Power supply: through USB bus or from an external.

On-board ADC, DAC, USB/JTAG terminal facility

Port pins are routed to header on mother board for easy connection and having:

8 General purpose input lines, 8 General purpose output lines, 16x2 LCD interface, 5 keys interface.

3 high speed digital outputs and 2 High speed digital input lines. 6 PWM outputs, 3 QEI inputs.

SPI bus for SPI slave interface,

9 Analog inputs, 2 Analog Universal outputs

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Input – 415V AC, Output – 3 Phase 400V, 10A suitable for 1.5 HP AC motor having proper heat dissipation arrangements

1200 V, 25 A diode rectifier with electrolyte DC capacitor for Input AC-DC conversion,

3 Phase Inverter Power Module with IGBT Rating @ 1200 V, 30 Amp with detailed protection and snubber circuits arrangement, interface circuit arrangement with controller using appropriate connectors, On-board driver circuit with protection and PWM isolation, IGBT with desaturation protection against overload and short-circuit.

Over current trip circuit is provided with trip status indicator, RESET switch.

Sensing circuit for three AC output currents, one DC current and one DC voltage. All connections terminated with banana connector.

# **Motor Setup**



Motor setup consist of Benn make

1 HP / 230 V / 3000 RPM / 4 Pole / 3 Phase / PMSM Motor with mechanical loading arrangement having linear scales.

Essential speed and other sensors as per control and feedback requirement.

# **Computer and Programing Arrangement**

Complete arrangement with personal computer having minimum following configuration is provided for programming the drive.

Intel Core-i3 (6th generation) 3.3 GHz processor, Mother Board - ASUS/GIGA-BITE or equivalent, RAM- 8 GB, Hard disk min.- 500 GB, DVD writer, Screen (18.5 Inch) – LG or equivalent, with required essential accessories.

Facility for self-written C program as well as model based programming.



# Digitally Controlled Four-Quadrant Chopper fed DC Motor Drive

### Model No.: NIAD05

## **Unique Features**

- Complete advanced learning platform
- Self-written program
- Model based program
- MATLAB/C language coding support
- Rapid development of control algorithm

### Control

Forward and reverse motoring operation with first and third quadrant chopper operation

Open Loop and Closed Loop Control

### Controller

ARM Cortex M4 32 bit Microcontrollers

Generic industry standard platform

### **Drives Consist of**

DC Shunt Motor with mechanical loading

Digital controller based on STM32F407VG uC

High power rectifier, DC link capacitor, inverter

Sensing circuits for AC/DC current, DC voltage and speed

# Performance Investigation of Digitally and Computerized Controlled Four-Quadrant Operation of DC Motor Drive

Electrical drive for studying four quadrant chopper fed DC Motor drive using latest ARM Cortex M4 32 bit Microcontrollers.

# Motor Controller



ARM Cortex M4 32-bit microcontroller for programming (STM32F407VGT6 microcontroller featuring 32-bit ARM Cortex-M4F core)

STM32F407VGT6 ARM Cortex-M4 Board featuring 32-bit ARM Cortex-M4F core, 168 MHz, 1 MB Flash, 192 KB RAM in an LQFP100 package.

On-board ST-LINK/V2 for programming and debugging with selection mode switch, Power supply: through USB bus or from an external.

On-board ADC, DAC, USB/JTAG terminal facility

Port pins are routed to header on mother board for easy connection and having:

8 General purpose input lines, 8 General purpose output lines, 16x2 LCD interface, 5 keys interface.

3 high speed digital outputs and 2 High speed digital input lines. 6 PWM outputs, 3 QEI inputs.

SPI bus for SPI slave interface,

9 Analog inputs, 2 Analog Universal outputs

D-type connector for RS232 interfaces.

Category: Advanced Electrical Drives

# High Power Module with Protection

#### Contact

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Input – 230V single phase AC, Output – 220V DC suitable for 1.5 HP DC motor having proper heat dissipation arrangements

1200 V, 25 A diode rectifier with electrolyte DC capacitor for Input AC-DC conversion,

Inverter Power Module with IGBT Rating @ 1200 V, 30 Amp with detailed protection and snubber circuits arrangement, interface circuit arrangement with controller using appropriate connectors, On-board driver circuit with protection and PWM isolation, IGBT with desaturation protection against overload and short-circuit.

Over current trip circuit is provided with trip status indicator, RESET switch.

Sensing circuit for three AC output currents, one DC current and one DC voltage. All connections terminated with banana connector.

# **Motor Setup**



Motor setup consist of Benn make

1.5 HP, 220V, 1500 rpm, DC Shunt Motor with spring balance load arrangement for loading

Essential speed and other sensors as per control and feedback requirement.

# **Computer and Programing Arrangement**

Complete arrangement with personal computer having minimum following configuration is provided for programming the drive.

Intel Core-i3 (6th generation) 3.3 GHz processor, Mother Board - ASUS/GIGA-BITE or equivalent, RAM- 8 GB, Hard disk min.- 500 GB, DVD writer, Screen (18.5 Inch) – LG or equivalent, with required essential accessories.

Facility for self-written C program as well as model based programming.



# Single Phase Dual Converters fed DC Motor Drive

Computerized Controlled Four-Quadrant

Operation of DC Motor using 1-Phase Dual

Converters with analysis of Circulating and Non

Electrical drive for studying single phase dual converter working in circulating

and non-circulating mode using latest ARM Cortex M4 32 bit Microcontrollers.

Investigation of Digitally

### Model No.: NIADO6

#### Category: Advanced Electrical Drives

and

# **Unique Features**

Performance

**Circulating Modes.** 

- Complete advanced learning platform
- Self-written program
- Model based program
- MATLAB/C language coding support
- Rapid development of control algorithm

### **Control Methods**

Circulating Current Mode of Operation

Non-circulating Current Mode of Operation

Open Loop and Closed Loop Control



ARM Cortex M4 32-bit microcontroller for programming (STM32F407VGT6 microcontroller featuring 32-bit ARM Cortex-M4F core)

STM32F407VGT6 ARM Cortex-M4 Board featuring 32-bit ARM Cortex-M4F core, 168 MHz, 1 MB Flash, 192 KB RAM in an LQFP100 package.

On-board ST-LINK/V2 for programming and debugging with selection mode switch, Power supply: through USB bus or from an external.

On-board ADC, DAC, USB/JTAG terminal facility

Port pins are routed to header on mother board for easy connection and having:

8 General purpose input lines, 8 General purpose output lines, 16x2 LCD interface, 5 keys interface.

3 high speed digital outputs and 2 High speed digital input lines. 6 PWM outputs, 3 QEI inputs.

SPI bus for SPI slave interface, 9 Analog inputs, 2 Analog Universal outputs

D-type connector for RS232 interfaces.

### Controller

ARM Cortex M4 32 bit Microcontrollers

Generic industry standard platform

### **Drives Consist of**

DC Shunt Motor with mechanical loading

Digital controller based on STM32F407VG uC

High power thyristor bridge with Inductor

Sensing circuits for DC current, DC voltage and speed

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# High Power Module with Protection



Input – 230V, 50 Hz single phase AC, Output – 220V DC suitable for 1.5 HP DC motor having proper heat dissipation arrangements

800 V, 25 A thyristor rectifier with circulating inductor for AC-DC conversion,

Observation of gate pulses and speed sensor outputs

Provision to operate in Open loop and closed loop speed control of motor.

Sensing circuit for DC current.

All connections terminated with banana connector.

### **Motor Setup**



Motor setup consist of Benn make

1.5 HP, 220V, 1500 rpm, DC Shunt Motor with spring balance load arrangement for loading

Essential speed and other sensors as per control and feedback requirement.

### Computer and Programing Arrangement

Complete arrangement with personal computer having minimum following configuration is provided for programming the drive.

Intel Core-i3 (6th generation) 3.3 GHz processor, Mother Board - ASUS/GIGA-BITE or equivalent, RAM- 8 GB, Hard disk min.- 500 GB, DVD writer, Screen (18.5 Inch) – LG or equivalent, with required essential accessories.

Facility for self-written C program as well as model based programming.



# Digitally Controlled Singlephase Controlled Rectifier fed DC Motor Drive

### Model No.: NIAD07

### Category: Advanced Electrical Drives

### **Unique Features**

- Complete advanced learning platform
- Self-written program
- Model based program
- MATLAB/C language coding support
- Rapid development of control algorithm
- Control Methods: Open Loop and Closed Loop Control

### Controller

ARM Cortex M4 32 bit Microcontrollers

Generic industry standard platform

### **Drives Consist of**

DC Shunt Motor with mechanical loading

Digital controller based on STM32F407VG uC

High power thyristor bridge with Inductor

Sensing circuits for DC current, DC voltage and speed

# Performance Investigation of Digitally controlled single-phase controlled rectifier fed DC Motor Drive.

Electrical drive for studying single phase controlled rectifier fed DC motor drives using latest ARM Cortex M4 32 bit Microcontrollers.

# Motor Controller



ARM Cortex M4 32-bit microcontroller for programming (STM32F407VGT6 microcontroller featuring 32-bit ARM Cortex-M4F core)

STM32F407VGT6 ARM Cortex-M4 Board featuring 32-bit ARM Cortex-M4F core, 168 MHz, 1 MB Flash, 192 KB RAM in an LQFP100 package.

On-board ST-LINK/V2 for programming and debugging with selection mode switch, Power supply: through USB bus or from an external.

On-board ADC, DAC, USB/JTAG terminal facility

Port pins are routed to header on mother board for easy connection and having:

8 General purpose input lines, 8 General purpose output lines, 16x2 LCD interface, 5 keys interface.

3 high speed digital outputs and 2 High speed digital input lines. 6 PWM outputs, 3 QEI inputs.

SPI bus for SPI slave interface, 9 Analog inputs, 2 Analog Universal outputs

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# High Power Module with Protection



Input – 230 V, 50 Hz single phase AC, Output – 220V DC suitable for 1.5 HP DC motor having proper heat dissipation arrangements

800 V, 25 A thyristor rectifier with circulating inductor for AC-DC conversion,

Observation of gate pulses and speed sensor outputs

Provision to operate in Open loop and closed loop speed control of motor.

Sensing circuit for DC current.

All connections terminated with banana connector.

# **Motor Setup**



Motor setup consist of Benn make

1.5 HP, 220V, 1500 rpm, DC Shunt Motor with spring balance load arrangement for loading

Essential speed and other sensors as per control and feedback requirement.

# **Computer and Programing Arrangement**

Complete arrangement with personal computer having minimum following configuration is provided for programming the drive.

Intel Core-i3 (6th generation) 3.3 GHz processor, Mother Board - ASUS/GIGA-BITE or equivalent, RAM- 8 GB, Hard disk min.- 500 GB, DVD writer, Screen (18.5 Inch) – LG or equivalent, with required essential accessories.

Facility for self-written C program as well as model based programming.

![](_page_14_Picture_0.jpeg)

# Digitally Controlled Switched Reluctance Motor Drive

#### Model No.: NIADO8

Category: Advanced Electrical Drives

### **Unique Features**

- Complete advanced learning platform
- Self-written program
- Model based program
- MATLAB/C language coding support
- Rapid development of control algorithm

# Controller

ARM Cortex M4 32 bit Microcontrollers

Generic industry standard platform

### **Drives Consist of**

SRM Motor with mechanical loading

Digital controller based on STM32F407VG uC

High power IGBT power module

Sensing circuits for DC current, DC voltage and speed

# Performance Investigation of digitally controlled Switched Reluctance Motor Drive.

Electrical drive for studying switched reluctance motor drives using latest ARM Cortex M4 32 bit Microcontrollers.

# Motor Controller

![](_page_14_Picture_21.jpeg)

ARM Cortex M4 32-bit microcontroller for programming (STM32F407VGT6 microcontroller featuring 32-bit ARM Cortex-M4F core)

STM32F407VGT6 ARM Cortex-M4 Board featuring 32-bit ARM Cortex-M4F core, 168 MHz, 1 MB Flash, 192 KB RAM in an LQFP100 package.

On-board ST-LINK/V2 for programming and debugging with selection mode switch, Power supply: through USB bus or from an external.

On-board ADC, DAC, USB/JTAG terminal facility

Port pins are routed to header on mother board for easy connection and having:

8 General purpose input lines, 8 General purpose output lines, 16x2 LCD interface, 5 keys interface.

3 high speed digital outputs and 2 High speed digital input lines. 6 PWM outputs, 3 QEI inputs.

SPI bus for SPI slave interface, 9 Analog inputs, 2 Analog Universal outputs

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# High Power Module with Protection

![](_page_15_Picture_7.jpeg)

Input – 230V single phase AC, Output – 220V DC suitable for 1.5 HP DC motor having proper heat dissipation arrangements

1200 V, 25 A diode rectifier with electrolyte DC capacitor for Input AC-DC conversion,

Inverter Power Module with IGBT Rating @ 1200 V, 30 Amp with detailed protection and snubber circuits arrangement, interface circuit arrangement with controller using appropriate connectors, On-board driver circuit with protection and PWM isolation, IGBT with desaturation protection against overload and short-circuit.

Over current trip circuit is provided with trip status indicator, RESET switch.

Sensing circuit for three AC output currents, one DC current and one DC voltage. All connections terminated with banana connector.

### **Motor Setup**

![](_page_15_Picture_14.jpeg)

Motor setup consist of Benn make

1 HP, 3000 rpm, 8/6 Switched Reluctance Motor with spring balance load arrangement for loading

Essential speed and other sensors as per control and feedback requirement.

# **Computer and Programing Arrangement**

Complete arrangement with personal computer having minimum following configuration is provided for programming the drive.

Intel Core-i3 (6th generation) 3.3 GHz processor, Mother Board - ASUS/GIGA-BITE or equivalent, RAM- 8 GB, Hard disk min.- 500 GB, DVD writer, Screen (18.5 Inch) – LG or equivalent, with required essential accessories.

Facility for self-written C program as well as model based programming.